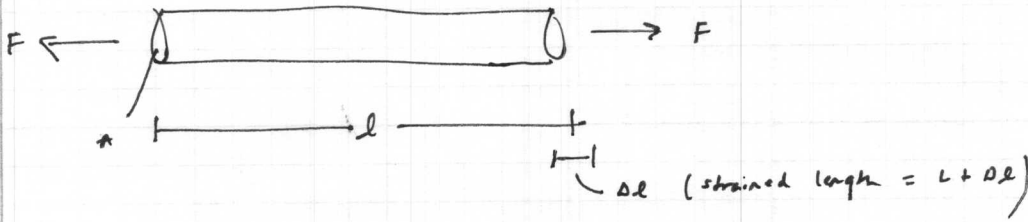


in a macroscopic solid, we have simple linear-elastic behavior

e.g. a bar in uniaxial tension



← young's modulus [ $N/m^2$ ]

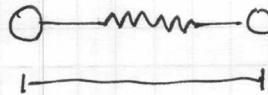
$$\sigma = \frac{F}{A} = E \epsilon$$

$$\epsilon = \frac{\Delta L}{L}$$

$$\frac{F}{A} = E \frac{\Delta L}{L} \Rightarrow \Delta L = \frac{FL}{AE} \quad \text{we'll return here later.}$$

at a far smaller scale, let's consider a material as a massive array of springs

→ each bond is like a spring



this is modeled by an interatomic potential,

$$x_0 = r_e$$

← equilibrium separation

e.g., the Morse potential

$$V = D \left[ \left( 1 - e^{-\beta(r-r_0)} \right)^2 - 1 \right]$$

↑ well "depth"

↖  $\beta = \text{well width.}$

$$V(x) = \text{energy [J]}$$

$$\frac{dV}{dx} = \text{force [N]}$$

$$\frac{d^2V}{dx^2} = \text{stiffness [N/m]}$$

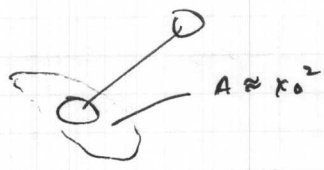
thus, if our "material" is a single bond spring

the restoring force  $F = s(x - x_0)$

↑  
stiffness.

↘ equilibrium length.

define "area" =  $\frac{1}{x_0^2}$



strain =  $\frac{\Delta l}{l} = \epsilon$

then stress =  $\frac{F}{A} = \frac{F}{x_0^2} = \frac{s(x - x_0)}{x_0^2} = \frac{s}{x_0} \left( \frac{x - x_0}{x_0} \right)$

↖ modulus  $[N/m^2] = E$

let's approximate some real values.

based on interatomic potentials.

- covalent bonds,  $s = 20 - 200 \text{ N/m}$
  - metal/ionic bonds,  $s = 15 - 100 \text{ N/m}$
  - polymers,  $s = 0.5 - 1 \text{ N/m}$
- } c-k bonds dominate springs in series

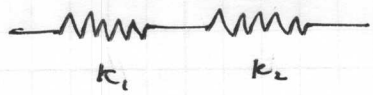
thus, if  $E \approx \frac{s}{x_0}$

(c-k bonds are weak)

$x_0 = 0.2 \text{ nm}$

$s = 200 \text{ N/m}$

$E \approx 1000 \text{ GPa} = \text{graphite!}$



$k_{eff} = \left( \frac{k_1 + k_2}{k_1 k_2} \right)^{-1}$

if  $k_1 \ll k_2 \Rightarrow k_{eff} = k_1$

stress can typically be close to the theoretical limit

strength, no. ... it is governed by defects, slip (e.g. grain boundaries)

and can be as low as  $10^{-4}E$ ; in nanoscopic materials, we can reach theoretical strength limits.

strength, lets say bonds break @ 10% elongation.

$$\epsilon = \frac{\sigma}{k_0} \left( \frac{k - k_0}{k_0} \right) \quad \Rightarrow \quad \epsilon \approx 0.1 E$$

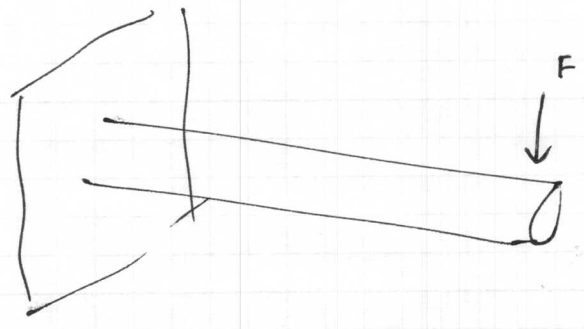
$\underbrace{\hspace{10em}}_{= 0.1}$ 
 $\searrow$  see Ashby plot.

in polymer fibers, chain alignment is very high  $\Rightarrow$  we approach theoretical strength, but are away from strength limit, which is practically governed by chain - chain gaps.

defects are stress concentrators.

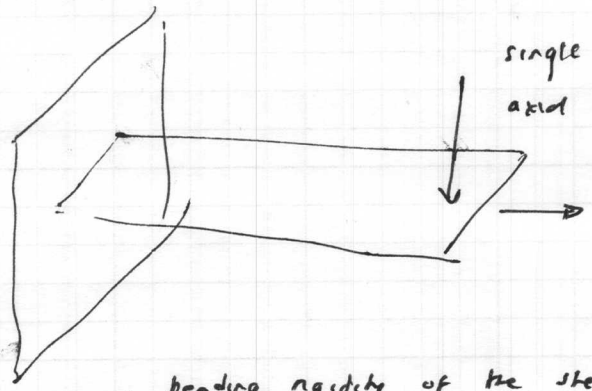
case study: consider CNTs or beams? w/ "continuum properties"?

assume yes - CNT is a continuous isotropic hollow cylinder.



$$d = FL^3 / 3EI$$

this is true if we choose E and t correctly



single graphene sheet => will have different axial (in-plane) and bending rigidities.

=> is this true for a SWNT too?

bending rigidity of the sheet =  $D = \frac{Et^3}{12(1-\nu^2)}$  [N·m]

$\nu = 0.16 - 0.34$

in-plane rigidity  $c = Et$

Both can be calculated based on bond rigidity (C-C hexagons) with no specification of t.

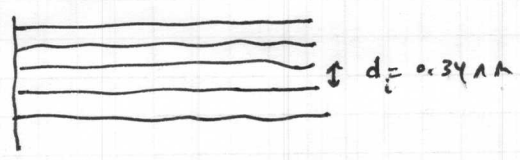
combining theory and experiment, for graphene we get

$$E = 5 \text{ TPa.}$$

$$t = 0.07 \text{ nm}$$

for a single layer

if we have multiple layers,



$$\Rightarrow E = 1 \text{ TPa}, \quad d = 0.34 \text{ nm}.$$

back to the CNT in bending,

the flexural rigidity  $EI = E \pi \frac{D_o^4}{64} \left( 1 - \left( \frac{D_i}{D_o} \right)^4 \right) = E \pi \frac{D_o^4}{64} \left( 1 - \left( 1 - \left( \frac{2t}{D_o} \right) \right)^4 \right)$

from  $E = \frac{\pi D_o^4}{64} - \frac{\pi D_i^4}{64}$

if  $t \ll D_o$ ,  $\left( 1 - \frac{2t}{D_o} \right)^4 \approx 1 - 4 \left( \frac{2t}{D_o} \right)$

$$\Rightarrow EI = \frac{E \pi D_o^4}{64} \cdot \frac{8t}{D_o} = \frac{\pi}{8} D_o^3 E t$$

$E t =$  in-plane graphene stiffness  $\times$  thickness.

so, we can use (1 TPa, 0.34 nm)  
or (5 TPa, 0.07 nm)

$\Rightarrow$  and for many-walled CNTs,  $t = 0.07 \text{ nm}$   
5 TPa

$$E_N = \frac{N}{N-1 + (t/d_i)} \frac{t}{d_i} E$$

$d_i =$  interlayer spacing

as  $N \rightarrow$  large,

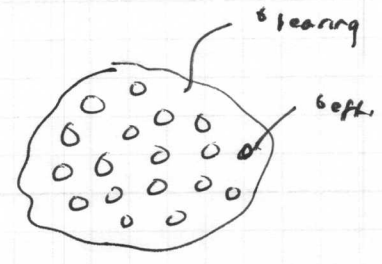
$$E_N \Rightarrow \frac{t}{d_i} E \Rightarrow E_N = 1 \text{ TPa}.$$

now, let's consider pecking effects on effective stiffness and strength

for a SWNT, the true engineering area is  $d_o^2$

so,  $\sigma = F/A$  ← but this is the load-bearing area,  $\pi(d_o^2 - d_i^2)$

$$\sigma_{\text{effective}} = \sigma_{\text{bearing}} \left( \frac{\pi d_o^2}{\pi(d_o^2 - d_i^2)} \right)$$



similarly, for  $\Delta L = \frac{FL}{AE}$  ←  $E = E_{\text{effective}}$

e.g. for 1 nm dia SWNT,  $E_{\text{eff}} = 0.5 TPa$

AND, we need to consider the tightness of pecking

now, consider strength.

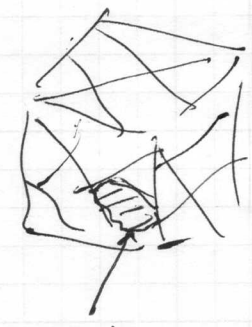
2 things: 1 - "top-down" grain size effects. => Hall-Petch.

2 - "bottom up" defect statistics in small values. => Weibull.

1 - Hall-Petch relation

strength of a bulk material increases as its grain size decreases... (to a point.)  
"grain boundary strengthening"

- grain boundaries hinder dislocation motion
- different grains have different crystal orientations
- dislocations "pile up" at grain boundaries



Hall-Petch relation

$$\sigma_y = \sigma_0 + \frac{K_y}{\sqrt{d}}$$

$\sigma_y$  ← strength coefficient  
 $\sqrt{d}$  ← grain size

material specific "sliding stress"

heat treatment, quenching affect grain size

crystals have theoretically high strength, but defects weaken crystals => grain boundaries "stop" failure.

also can introduce particles as nucleants.

but as grain size decreases below 10-100 nm, Hall-Petch breaks down, => can have  $K < 0$

- no consensus on mechanism
- grain boundary sliding
- diffusion (lots of surface atoms)

2 - statistics of failure

Weibull statistic

Volume or surface flows?

probability of failure  $F(s_f) = 1 - \exp\left(-\left(\frac{s_f}{\alpha}\right)^\beta\right)$

$\beta$  = "slope" parameter (dimensionless)

$\alpha$  = scale parameter.

QFM model:  $\sigma_f(N) = \sigma_c \left(1 + \frac{\rho}{2a}\right)^{1/2} (1+n)^{-1/2}$

$\rho$  = "rupture radius"

$a$  = lattice parameter

$\sigma_c$  = perfect (defect-free) strength

$n$  = "obns"

=> see Asheri paper.

finally, how many defects are there.

activation energy => vacancy (just one type of defect - there are many)

$c_v = \text{equilibrium concentration} = \exp(-q/kT)$  (vacancy formation energy)

for a sphere,  $N_{\text{atoms}} = n_v \left(\frac{4\pi}{3}\right) r^3$

if  $c_v N_{\text{atoms}} < 1$ , no vacancies



$$n_v \left( \frac{4}{3} \pi \right) r^3 \exp(-\phi/kT) < 1$$

$$r < \left\{ \exp(\phi/kT) \left( \frac{3}{4\pi} \right) \right\}^{1/3}$$

=> for Al,  $\phi = 0.66 \text{ eV}$ ,  $900 \text{ K}$  =>  $d = 6 \text{ nm}$ .

CNTs: 1 nm diameter, very long defect-free segment!